Bayesian Analysis Users Guide
Release 4.00, Manual Version 1

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## Contents

Manual Status 14

1 An Overview Of The Bayesian Analysis Software 17
   1.1 The Server Software ........................................ 17
   1.2 The Client Interface ...................................... 20
       1.2.1 The Global Pull Down Menus ......................... 22
       1.2.2 The Package Interface ................................. 22
       1.2.3 The Viewers .......................................... 25

2 Installing the Software 27

3 the Client Interface 29
   3.1 The Global Pull Down Menus .............................. 31
       3.1.1 the Files menu .................................. 31
       3.1.2 the Packages menu .................................. 36
       3.1.3 the WorkDir menu .................................. 41
       3.1.4 the Settings menu .................................. 42
       3.1.5 the Utilities menu .................................. 46
       3.1.6 the Help menu ..................................... 47
   3.2 The Submit Job To Server area ......................... 47
   3.3 The Server area .......................................... 48
   3.4 Interface Viewers ....................................... 49
       3.4.1 the Ascii Data Viewer ................................ 49
       3.4.2 the fid Data Viewer .................................. 51
       3.4.3 Image Viewer ........................................ 56
           3.4.3.1 the Image List area ............................ 56
           3.4.3.2 the Set Image area ............................. 58
           3.4.3.3 the Image Viewing area ......................... 58
           3.4.3.4 the Grayscale area on the bottom ............... 60
           3.4.3.5 the Pixel Info area ............................. 60
           3.4.3.6 the Image Statistics area ......................... 60
       3.4.4 Prior Viewer ........................................ 62
       3.4.5 fid Model Viewer ...................................... 65
           3.4.5.1 The fid Model Format ............................ 65
<table>
<thead>
<tr>
<th>Section</th>
<th>Page</th>
</tr>
</thead>
<tbody>
<tr>
<td>8.5 Outputs From The Bayes Analyze Package</td>
<td>167</td>
</tr>
<tr>
<td>8.5.1 The “bayes.params.nnnn” and “bayes.model.nnnn” Files</td>
<td>169</td>
</tr>
<tr>
<td>8.5.1.1 The Bayes Analyze File Header</td>
<td>169</td>
</tr>
<tr>
<td>8.5.1.2 The Global Parameters</td>
<td>174</td>
</tr>
<tr>
<td>8.5.1.3 The Model Components</td>
<td>175</td>
</tr>
<tr>
<td>8.5.2 The “bayes.output.nnnn” File</td>
<td>177</td>
</tr>
<tr>
<td>8.5.3 The “bayes.probabilities.nnnn” File</td>
<td>181</td>
</tr>
<tr>
<td>8.5.4 The “bayes.log.nnnn” File</td>
<td>184</td>
</tr>
<tr>
<td>8.5.5 The “bayes.status.nnnn” and “bayes.accepted.nnnn” Files</td>
<td>187</td>
</tr>
<tr>
<td>8.5.5.1 The “bayes.model.nnnn” File</td>
<td>188</td>
</tr>
<tr>
<td>8.5.6 The “bayes.summary1.nnnn” File</td>
<td>189</td>
</tr>
<tr>
<td>8.5.7 The “bayes.summary2.nnnn” File</td>
<td>190</td>
</tr>
<tr>
<td>8.5.8 The “bayes.summary3.nnnn” File</td>
<td>191</td>
</tr>
<tr>
<td>8.6 Bayes Analyze Error Messages</td>
<td>192</td>
</tr>
<tr>
<td>9 Big Peak/Little Peak</td>
<td>197</td>
</tr>
<tr>
<td>9.1 The Bayesian Calculation</td>
<td>199</td>
</tr>
<tr>
<td>9.2 Outputs From The Big Peak/Little Peak Package</td>
<td>206</td>
</tr>
<tr>
<td>10 Metabolic Analysis</td>
<td>209</td>
</tr>
<tr>
<td>10.1 The Metabolic Model</td>
<td>213</td>
</tr>
<tr>
<td>10.2 The Bayesian Calculation</td>
<td>215</td>
</tr>
<tr>
<td>10.3 The Metabolite Models</td>
<td>218</td>
</tr>
<tr>
<td>10.3.1 The IPGD_D2O Metabolite</td>
<td>218</td>
</tr>
<tr>
<td>10.3.2 The Glutamate.2.0 Metabolite</td>
<td>222</td>
</tr>
<tr>
<td>10.3.3 The Glutamate.3.0 Metabolite</td>
<td>225</td>
</tr>
<tr>
<td>10.4 The Example Metabolite</td>
<td>226</td>
</tr>
<tr>
<td>10.5 Outputs From The Bayes Metabolite Package</td>
<td>228</td>
</tr>
<tr>
<td>11 Find Resonances</td>
<td>229</td>
</tr>
<tr>
<td>11.1 The Bayesian Calculations</td>
<td>231</td>
</tr>
<tr>
<td>11.2 Outputs From The Bayes Find Resonances Package</td>
<td>236</td>
</tr>
<tr>
<td>12 Diffusion Tensor Analysis</td>
<td>237</td>
</tr>
<tr>
<td>12.1 The Bayesian Calculation</td>
<td>239</td>
</tr>
<tr>
<td>12.2 Using The Package</td>
<td>244</td>
</tr>
<tr>
<td>13 Big Magnetization Transfer</td>
<td>249</td>
</tr>
<tr>
<td>13.1 The Bayesian Calculation</td>
<td>249</td>
</tr>
<tr>
<td>13.2 Outputs From The Big Magnetization Transfer Package</td>
<td>252</td>
</tr>
<tr>
<td>14 Magnetization Transfer</td>
<td>255</td>
</tr>
<tr>
<td>14.1 The Bayesian Calculation</td>
<td>257</td>
</tr>
<tr>
<td>14.2 Using The Package</td>
<td>261</td>
</tr>
</tbody>
</table>
# List of Figures

<table>
<thead>
<tr>
<th>Figure</th>
<th>Description</th>
<th>Page</th>
</tr>
</thead>
<tbody>
<tr>
<td>1.1</td>
<td>The Start Up Window</td>
<td>21</td>
</tr>
<tr>
<td>1.2</td>
<td>Example Package Interface</td>
<td>23</td>
</tr>
<tr>
<td>3.1</td>
<td>The Start Up Window</td>
<td>30</td>
</tr>
<tr>
<td>3.2</td>
<td>The Files Menu</td>
<td>31</td>
</tr>
<tr>
<td>3.3</td>
<td>The Load Image Selection Menu</td>
<td>33</td>
</tr>
<tr>
<td>3.4</td>
<td>The Packages Menu</td>
<td>37</td>
</tr>
<tr>
<td>3.5</td>
<td>The Working Directory Pull Down Menu</td>
<td>42</td>
</tr>
<tr>
<td>3.6</td>
<td>The Working Directory Pop up</td>
<td>43</td>
</tr>
<tr>
<td>3.7</td>
<td>The Settings Pull Down Menu</td>
<td>44</td>
</tr>
<tr>
<td>3.8</td>
<td>The McMC Parameters Pop up</td>
<td>44</td>
</tr>
<tr>
<td>3.9</td>
<td>The Edit Server Popup</td>
<td>45</td>
</tr>
<tr>
<td>3.10</td>
<td>The Submit Job Widget Group</td>
<td>48</td>
</tr>
<tr>
<td>3.11</td>
<td>The Server Widget Group</td>
<td>49</td>
</tr>
<tr>
<td>3.12</td>
<td>the Ascii Data viewer</td>
<td>50</td>
</tr>
<tr>
<td>3.13</td>
<td>the fid Data viewer</td>
<td>52</td>
</tr>
<tr>
<td>3.14</td>
<td>The Fid Data Viewer Display Type</td>
<td>53</td>
</tr>
<tr>
<td>3.15</td>
<td>The Fid Data Viewer the Options Menu</td>
<td>54</td>
</tr>
<tr>
<td>3.16</td>
<td>The Image Viewer</td>
<td>57</td>
</tr>
<tr>
<td>3.17</td>
<td>The Image Viewer Right Mouse Menu</td>
<td>58</td>
</tr>
<tr>
<td>3.18</td>
<td>The Prior Viewer</td>
<td>63</td>
</tr>
<tr>
<td>3.19</td>
<td>The Fid Model Viewer</td>
<td>66</td>
</tr>
<tr>
<td>3.20</td>
<td>The Data Model and Residuals</td>
<td>69</td>
</tr>
<tr>
<td>3.21</td>
<td>The Plot Information popup</td>
<td>70</td>
</tr>
<tr>
<td>3.22</td>
<td>The Posterior Probabilities</td>
<td>71</td>
</tr>
<tr>
<td>3.23</td>
<td>The Posterior Probabilities Vs Parameter Value</td>
<td>73</td>
</tr>
<tr>
<td>3.24</td>
<td>The Posterior Probabilities Vs Parameter Value a Skewed Example</td>
<td>74</td>
</tr>
<tr>
<td>3.25</td>
<td>The Expected Log Likelihood</td>
<td>76</td>
</tr>
<tr>
<td>3.26</td>
<td>The Scatter Plots</td>
<td>77</td>
</tr>
<tr>
<td>3.27</td>
<td>The Log Probability Plot</td>
<td>79</td>
</tr>
<tr>
<td>3.28</td>
<td>The Text Results Viewer</td>
<td>81</td>
</tr>
<tr>
<td>3.29</td>
<td>The Bayes Condensed File</td>
<td>84</td>
</tr>
<tr>
<td>3.30</td>
<td>Fortran/C Model Viewer</td>
<td>87</td>
</tr>
<tr>
<td>3.31</td>
<td>Fortran/C Model Viewer</td>
<td>88</td>
</tr>
</tbody>
</table>
27.1 Nonlinear Phasing Example ............................................. 356
27.2 Nonlinear Phasing Interface ............................................. 360

28.1 Image Pixels Example ..................................................... 362

A.1 Ascii Data File Format ..................................................... 368

D.1 The McMC Values Report Header ........................................ 386
D.2 McMC Values Report, The Middle ...................................... 387
D.3 The McMC Values Report, The End ..................................... 388

E.1 Writing Models A Fortran Example ...................................... 392
E.2 Writing Models A C Example ............................................. 393
E.3 Writing Models, The Parameter File .................................... 395
E.4 Writing Models Fortran Declarations ................................... 399
E.5 Writing Models Fortran Example ......................................... 402
E.6 Writing Models The Parameter File ..................................... 403

G.1 The FD File Header ......................................................... 409

H.1 the Posterior Probability for the Number of Outliers ................. 412
H.2 The Data, Model and Residual Plot With Outliers .................... 414
List of Tables

8.1 Multiplet Relative Amplitudes ............................................. 157
8.2 Bayes Analyze Models ........................................................... 173
8.3 Bayes Analyze Short Descriptions ........................................... 186
Chapter 11

Find Resonances

There are two frequency finding programs in the Bayesian Analysis Software: Bayes Analyze, Chapter 8, and Bayes Find Resonance. Bayes Analyze is a searching algorithm that uses the residuals from the current fit, to determine if there is evidence in the data for and additional resonance. While this procedure is implemented using Bayesian probability theory, it is still an approximation to computing the full Bayesian posterior probability for the number of resonances. We implemented Bayes Analyze in this way, so that it would be very fast. However, under some conditions, Bayes Analyze will miss resonances when they are either very close together or the signal-to-noise of the resonance is vary low. To solve these problems, we implemented a frequency finding program that uses Markov chain Monte Carlo to compute the posterior probability for the number of resonances. The interface to the find resonance package is shown in Fig. 11.1 To use this package, you must do the following:

Select the Bayes Find Resonances package from the Package menu.

Load the Fid data that is to be analyzed. If the Fid is arrayed, select the trace that is to be analyzed. The trace analyzed is the currently displayed trace. At the present time only a single Fid is processed by Bayes Find Resonances package.

Select the phase model, the choices are correlated, uncorrelated and automatic.

- If the phase model is “Common,” the all resonances have the same phase.
- If the phase model is “Independent,” the all resonances have a different phase.
- If the phase model is “Automatic,” then the Bayes Find Resonances package computes the posterior probability for the phase of each resonance.

Check the “Constant” box if the data contains an offset.

Set the first and last Fids that are to be analyzed. Note that these Fids are analyzed separately, not jointly, so you will get an analysis for each selected Fid.

Set the maximum number of resonances that can be included in a model.

Select the server that is to process the analysis.
Figure 11.1: When the Find Resonances package is selected, this is the displayed interface. To use this package, load the Fid you wish to analyze. The spectrum of this Fid will be displayed in the Fid Data Viewer. Select the Fid you wish to analyze and display that Fid. At the present time only a single Fid may be processed at one time. Set the various optional feature of the model you wish to use and run the analysis. When the analysis finishes use the “Build Model” button to select and build a model of the Fid. The Fid Model Viewer can then be used to view this model.
Check the status of the selected server to determine if the server is busy, change to another server if the selected server is busy.

Run the analysis on the selected server by activating the “Run” button.

Get the results of the analysis by activating the “Get Job” button. If the analysis is running, this button will return the Accepted report containing the status of the current run. Otherwise, it will fetch and display the results from the current analysis.

Unlike Bayes Analyze which outputs parameter estimates computed using the values that maximized the joint posterior probability for the parameters, Bayes Find Resonances outputs mean and standard deviation parameter estimates computed from all high probability models. That is to say if the probability for the number of resonances was 50% for 9 and 50% for 10 resonances, then there will be mean and standard deviation parameter estimates for the frequencies and decay rate constants from both of these models. Additionally, Bayes Find Resonances runs multiple Fids one right after the other. Consequently, when a Fid model of the time domain data is generated, you must specify both the resonance model and the number of the Fid to model. The Fid number to model is indicated using the “Model Fid Number” entry box. If there are multiples high probability resonance models, clicking on the “Build FID Model” button will show you a list of these models and you can select which one you wish to use in generating a time domain Fid model.

11.1 The Bayesian Calculations

The first step in all Bayesian calculations is to define the problem. Here, the problem is essentially a parameter estimation calculations where one is estimating the frequencies, amplitudes, decay rate constants and phases of multiple exponentially decaying sinusoidal. The model will designated as $M(t_i)$ where complex quantities will be in bold. Then symbolically the model which relates the complex data, model and noise is given by:

$$d_i = M(t_i) + n_i \quad (i \in \{1, \ldots, N\})$$

where $N$ is the total number of complex data values, $d_i$ is a complex data values sampled at time $t_i$, and $n_i$ is a complex noise value at time $t_i$. The complex model $M(t_i)$ is given by:

$$M(t_i) = [F\delta(t_i) + C \delta(\nu) + \sum_{j=1}^{m} A_j \exp\{2\pi i f_j(t_i - t_0) - \alpha_j t_i + i\phi \delta(\xi_j) + i\phi_j[1 - \delta(\xi_j)]\}]$$

where $F$ is a model of the first data value, the function $\delta(\cdot)$ is defined below, $C$ is a complex offset, $m$ is the unknown number of sinusoids, $A_j$ is the amplitude of the $j$th sinusoid, $f_j$ is the frequency of the $j$th sinusoid, $t_0$ is a first order phase correction, $\alpha_j$ is the decay rate constant of the $j$th sinusoid. The quantity “$\phi \delta(\xi_j) + \phi_j[1 - \delta(\xi_j)]$” is the phase of the $j$th sinusoid and is either a common zero order phase, $\phi$, or a unique phase specific to the $j$th sinusoid, $\phi_j$. Whether or not the phase is common or unique depends on the value of the indicator function $\delta(\xi_j)$. The indicator function $\delta(\cdot)$ is defined as

$$\delta(\nu) = \begin{cases} 1 & \text{If } \nu = 0 \\ 0 & \text{Otherwise} \end{cases}$$
so, for example, the quantity $F \delta(t_i)$ is present only when $t_i = 0$. Similarly, the common phase $\phi$ is present only when $\xi_j = 0$, where $\xi_j$ is a two value binary variable defined as:

$$\xi_j = \begin{cases} 
1 & \text{If the } j\text{th sinusoid has a common zero order phase} \\
0 & \text{Otherwise}
\end{cases} \quad (11.4)$$

Here common zero phase means that several sinusoids share the same zero order phase parameter.

The value of $\xi_j$ is under user control. If the user selects the “Common” phase model, then $\xi_j = 0$ for all sinusoids and all sinusoids share the same common zero order phase parameter. If the user selects the “Independent” phase model, then $\xi_j = 1$ for all sinusoids and all sinusoids have a unique zero order phase parameter $\phi_j$. Finally, if the user selects the phase model as “Independent” then the parameters $\xi_j$ are binary variables that are simulated in the Markov chain Monte Carlo simulation, i.e., the Bayes Find Resonances package automatically determines which resonances have common zero order phase and which have a unique zero order phase.

Whether or not the constant models are present is also under user control. If the “Constant” check box is activated, then $\nu$ is set equal to zero by the package and $\delta(\nu) = 1$ and in Eq (11.2) the constant models are present. If the constant check box is not active then $\nu = 1$ and no constants are present in Eq (11.2). However, unlike the phase model, the Bayes Find Resonances package does not simulate the binary variable $\nu$, this value is set by the user and the package uses the indicated value.

The Bayes Find Resonances package is a hybrid parameter estimation and model selection package. It is model selection in that it must determine how many resonances are present, and when the phase model is selected as “Independent” it must also estimate the binary parameters, $\xi_j$. So, the set of parameters estimated by Bayes Find Resonances package when all parameters are active, is:

- $\mathbf{F}$ is the complex first point model, it contains two constants $F_R$ and $F_I$, the real and imaginary first point parameters.
- $\mathbf{C}$ is the complex constant offset model, it contains two constants $C_R$ and $C_I$, which are the real and imaginary offset parameters.
- $m$ is the unknown number of sinusoids in the data.
- $A$ is the collection of amplitudes in the $m$ sinusoids, so $A \equiv \{A_1, \ldots, A_m\}$.
- $f$ is the collection of frequencies in the $m$ sinusoids, so $f \equiv \{f_1, \ldots, f_m\}$.
- $\alpha$ is the collection of decay rate constants in the $m$ sinusoids, so $\alpha \equiv \{\alpha_1, \ldots, \alpha_m\}$.
- $t_0$ is the first order phase in in the $m$ sinusoids.
- $\xi$ is the collection of phase model indicators in the $m$ sinusoids, so $\xi \equiv \{\xi_1, \ldots, \xi_m\}$.
- $\phi$ is the common zero order phase in the $j$th sinusoids when $\delta(\xi_j) = 1$.
- $\phi_j$ is the zero order phase in the $j$th sinusoids when $\delta(\xi_j) = 0$.

We are going to designate this collection of parameters as $\Phi$ and then proceed with the Bayesian calculations.
The Bayesian calculations are for the posterior probability for the number of resonances in the data set. This posterior probability is designated as \( P(m|DI) \), where \( D \) represents all of the data and \( I \) stands for all of the prior information. This posterior probability is computed by application of Bayes' Theorem:

\[
P(m|DI) = \frac{P(m|I)P(D|mI)}{P(D|I)} \tag{11.5}
\]

where \( p(m|I) \) is the prior probability for the number of resonances, \( P(D|mI) \) is the marginal direct probability for the data given the model order and \( P(D|I) \) is a marginal direct probability for the data given only the prior information \( I \). The direct probability for the data given only the prior information, \( P(D|I) \), is a normalization constant and is given by:

\[
P(D|I) = \sum_{m=1}^{\text{Max}} P(D|mI)
\tag{11.6}
\]

where the maximum number of resonances is designated as “Max.” Comparing Eq. (11.6) to Eq. (11.5) it is easy to see that \( P(D|I) \) is a normalization constant. If we normalize the posterior probability for the number of resonances, \( P(m|DI) \), at the end of the calculations, then Eq (11.5) becomes:

\[
P(m|DI) \propto P(m|I)P(D|mI). \tag{11.7}
\]

The prior probability for the number of resonances, \( P(m|I) \), is sufficiently simplified that we could assign it a numerical value. For now we will simply leave it in this symbolic form. However, the direct probability for the data given the number of resonances and the prior information, \( P(D|mI) \), is not yet sufficiently simplified so that its value can be assigned. To proceed with the calculation, one introduces the collection of parameters \( \Phi \) into this probability, the the direct probability for the data, \( P(D|mI) \), the posterior probability for the number of resonances becomes

\[
P(m|DI) \propto P(m|I) \int P(D\Phi|mI)d\Phi. \tag{11.8}
\]

One proceeds by applying the product rule to the right-hand side of this equation:

\[
P(m|DI) \propto P(m|I) \int P(\Phi|I)P(D|\Phi mI)d\Phi. \tag{11.9}
\]

Factoring the prior probability for all of the parameters, \( P(\Phi|I) \) into individual prior probabilities
THE PACKAGES

for each parameter, one obtains:

\[
P(m|DI) \propto P(m|I) \int P(F_R|I)P(F_I|I)P(C_R|I)P(C_I|I)
\]
\[
\times P(\phi|I)P(t_0|I)P(D|\Phi m I)
\]
\[
\times \left[ \prod_{j=1}^{m} P(A_j|I) \right]
\]
\[
\times \left[ \prod_{j=1}^{m} P(f_j|I) \right]
\]
\[
\times \left[ \prod_{j=1}^{m} P(\alpha_j|I) \right]
\]
\[
\times \left[ \prod_{j=1}^{m} P(\xi_j|I) \right]
\]
\[
\times \left[ \prod_{j=1}^{m} P(\phi_j|I)^{\delta(\xi_j)} \right] d\Phi.
\]

(11.10)

However, this is the marginal posterior probability for the number of resonances, and is the main output from the Bayes Find Resonances package. But the quantity sampled in the Markov chain Monte Carlo simulation is the joint posterior probability for all of the parameters. While this posterior probability is very similar, its not quite the same. The joint posterior probability for all of the parameters is given by:

\[
P(m\Phi|DI) \propto P(m|I)P(F_R|I)P(F_I|I)P(C_R|I)P(C_I|I)
\]
\[
\times P(\phi|I)P(t_0|I)P(D|\Phi m I)
\]
\[
\times \left[ \prod_{j=1}^{m} P(A_j|I) \right]
\]
\[
\times \left[ \prod_{j=1}^{m} P(f_j|I) \right]
\]
\[
\times \left[ \prod_{j=1}^{m} P(\alpha_j|I) \right]
\]
\[
\times \left[ \prod_{j=1}^{m} P(\xi_j|I) \right]
\]
\[
\times \left[ \prod_{j=1}^{m} P(\phi_j|I)^{\delta(\xi_j)} \right].
\]

(11.11)

which is Eq. (11.10) without the integrations. The prior probabilities are assigned as follows:

\(P(m|I)\) is assigned as an Exponential prior with \((0 \leq m \leq 50)\) where a model containing 50 resonances is a hard-coded maximum.

\(P(F_R|I)\) is assigned as a bounded Gaussian prior whose range is \(\pm 6 \times \) the amplitude of the first data value and whose standard deviation is three times the magnitude of the first data value.

\(P(F_I|I)\) is assigned the same as \(P(F_R|I)\) was assigned.

\(P(C_R|I)\) is assigned as a bounded Gaussian whose mean is equal to the average of the last 10 real data values and whose upper and lower bounds is 5 times the mean. Finally, the standard deviation of this prior is one fifth of the prior range.
$P(C_l|I)$ is assigned like $P(C_R|I)$ except the means and bounds are taken from the imaginary channel.

$P(\phi|I)$ is assigned a uniform prior probability ranging from zero to $2\pi$.

$P(t_0|I)$ essentially sets a time when the phases of all the sinusoids are the same. The prior probability for this time offset has a mean of zero, meaning that the phases are all expected to be the same at the start of the acquisition. However, we allow this parameter to range over $\pm 5$ dwell or sampling times, i.e., the zero of time could occur the equivalent of 5 data values before the start of the acquisition and up to 5 data value past the start of acquisition. However, the standard deviation of this Gaussian prior probability is only 0.3 data values. Indicating, that while $T_0$ is allowed to have a large range, in fact it is strongly suspected that its value is near zero.

$P(A_j|I)$ is assigned a bounded Gaussian prior probability for one of the amplitudes. Its mean is zero, it’s upper and lower bounds are 3 times the average magnitude of the first 10 complex data values and its standard deviation is two times that average. This prior is used for the prior probability for each resonance amplitude in the model.

$P(f_j|I)$ is assigned a uniform prior probability ranging over the entire sweep width of the data. This prior is used for the prior probability for each resonance frequency in the model.

$P(\alpha_j|I)$ is assigned a positive prior probability whose low is 0.001 in dimensionless units. The peak value is set to the current value of the “lb” parameter. The maximum value is set so that if the signal were decaying at this maximum, it will go through roughly 3 e-foldings in the first 9 data values. So the maximum value is strongly dependent on the sampling rate.

$P(\xi_j|I)$ is assigned a discrete uniform prior probability having two possible values, zero or one with zero indicating an independent phase and one indicating a common phase.

$P(\phi_j|I)$ is assigned a uniform prior probability ranging from zero to $2\pi$. In the above equations, 11.10 and 11.11, this probability is written as $P(\phi_j|I)^{\delta(\xi_j)}$, which is just a notational mechanism to indicate that the prior is either present or not. When $\delta(\xi_j) = 1$, $\xi_j = 0$, the phase model is independent and the prior is present. Similarly, when $\xi_j = 1$ the phase model is common and this prior is not present because the prior is raised to the zero power.

$P(D|\Phi m I)$ is the direct probability for the data given all of the parameters and the prior information and is assigned using a Gaussian prior probability for the noise. This probability is often called a likelihood or likelihood function.

The Markov chain simulation that implements this calculation targets the joint posterior probability for all of the parameters in the model, Eq. (11.11). It then uses Monte Carlo integration to obtain samples from the marginal posterior probability for each parameter appearing in the model. The samples from the marginal posterior probability for each parameter are then used to generate mean and standard deviation estimates of each parameter appearing in the model. Additionally, the samples are used to generate histograms. These histograms are crude estimates of the posterior probability for each parameter. In addition to outputting the histograms, the samples are also output and these samples can be used to generate Maximum Entropy histograms of the samples, see
Finally, these samples are used to compute the posterior probability for the number of resonances, Eq. (11.10).

If there are multiple high probability models in this posterior, i.e., the posterior probability for the number of resonances, \( P(m|DJ) \), has significant weight on several values of \( m \), then samples are drawn for each high probability model and these samples are used to generate histograms and parameter estimates given each high probability model. Consequently, then the algorithm finishes it is possible to have not one set of outputs but several. These outputs are viewed using the standard widgets. Additionally, it is possible to generate time domain Fid models for each high probability model.

### 11.2 Outputs From The Bayes Find Resonances Package

The Text outputs files from the Find Resonance packages consist of: “Bayes.prob.model,” “BayesFind-Res.mcmc.values,” “Bayes.params,” “Console.log,” “Bayes.accepted” and a “Bayes.Condensed.File.” These output files can be viewed using the Text Viewer or they can be viewed using File Viewer by navigating to the current working directory and then selecting the files. The format of the mcmc.values report is discussed in Appendix D and the other reports are discussed in Chapter 3. Additionally, the “Plot Results Viewer” can be used to view the output probability density functions. In addition to the standard data, model and residual plots there are probability density functions for the frequencies and decay rate constants, and the amplitudes for each resonance for each high probability model.

Finally, for each high probability model, there is an output “bayes.params.nnnn” and “bayes.model.nnnn” file where this file has exactly the same format as the Bayes Analyze Model file, see Chapter 8.5.5.1. These files are used in conjunction with the “Build FID Model” button to generate a time domain model of the input Fid data. When this button is activated the Fid and the selected bayes.model.nnnn file are sent to the server and the Bayes Model program, see Chapter 8.1 for a description of this program, is run. During this time the interface waits for the Bayes Model program to finish. When the interface detects that the model has been built, the interface fetches the model from the server, Fourier transforms the model and then displays the model using the Fid Model Viewer.
Bibliography


[43] Metropolis, Nicholas, Arianna W. Rosenbluth, Marshall N. Rosenbluth, Augusta H. Teller, and Edward Teller (1953), “Equation of State Calculations by Fast Computing Machines,” Journal of Chemical Physics. The previous link is to the American Institute of Physics and if you do not have access to Science Sitations you many not be able to retrieve this paper.


